

From Tangles to Links

A story of knots and Gaußian Differential Operators

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The ideal knot/link
invariant

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graph TD; A([The ideal knot/link invariant]) --> B([strong  
distinguishes knots/links well]); A --> C([computable  
Not more than polynomial-time computable in # of crossings]); A --> D([topological  
behaves well with knot structures we care about]);
```

strong

distinguishes
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computable

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topological

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Hopf Algebras

Mat
 $\mathbb{Q} \rightarrow \text{diag}$

①

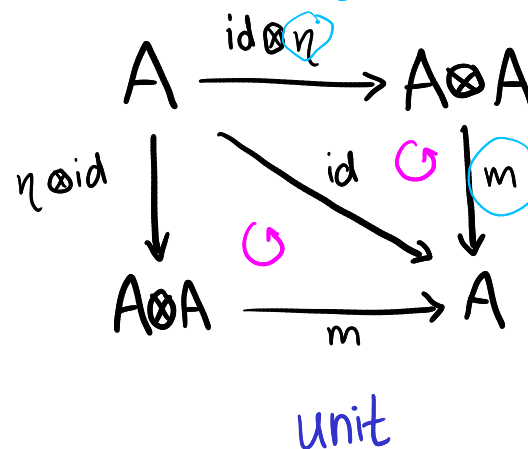
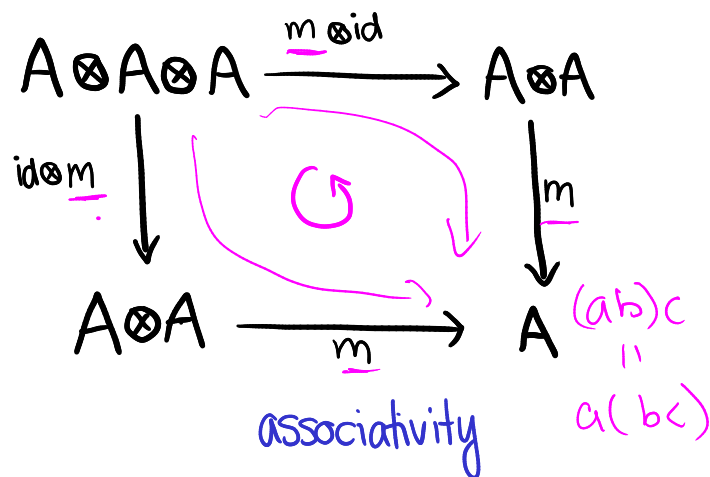
algebra structure:

- vector space A and tensor products $A \otimes A, A \otimes A \otimes A, \dots$

- multiplication $A \otimes A \xrightarrow{m} A$

- unit a map $\mathbb{k} \xrightarrow{\eta} A$ (define $1 := \eta(1) \in A$)

- relations:



$1 \in A \quad \forall a \in A$

$$1 \cdot a = a \cdot 1 = a$$

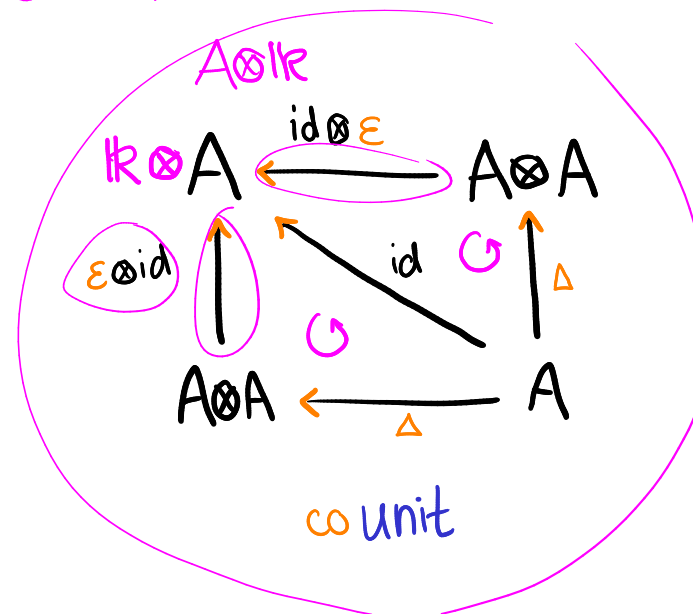
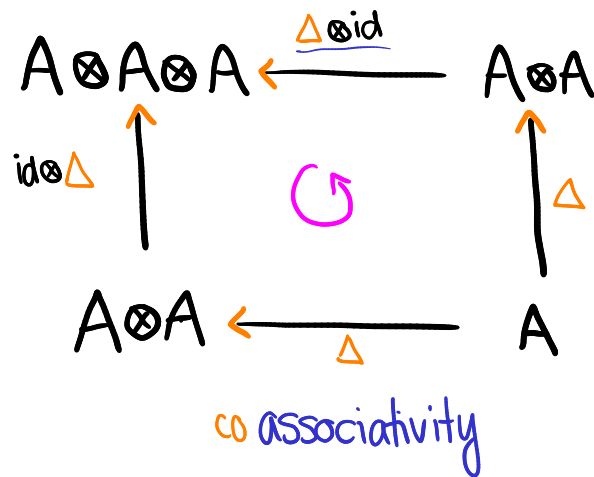
$$\eta(1) =: 1$$

$$\eta(r) = r \eta(1) = r \cdot 1$$

Hopf Algebras

② co algebra structure:

- vector space A and tensor products $A \otimes A, A \otimes A \otimes A, \dots$
- co multiplication $A \otimes A \xleftarrow{\Delta} A$ "diagonal" "doubling" "factorize"
- co unit a map $k \xleftarrow{\varepsilon} A$ } trivial rep.
- relations:



Hopf Algebras

③

bialgebra structure:

$$(a \otimes b) \cdot (c \otimes d)$$

$$= ac \otimes bd$$

- vector space A and tensor products $A \otimes A, A \otimes A \otimes A, \dots$

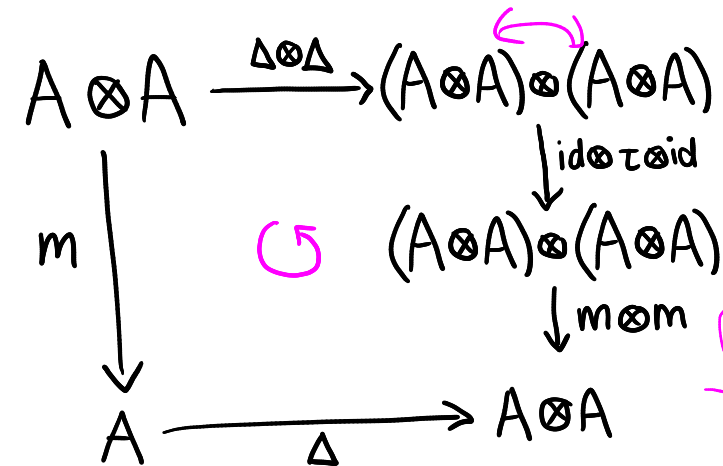
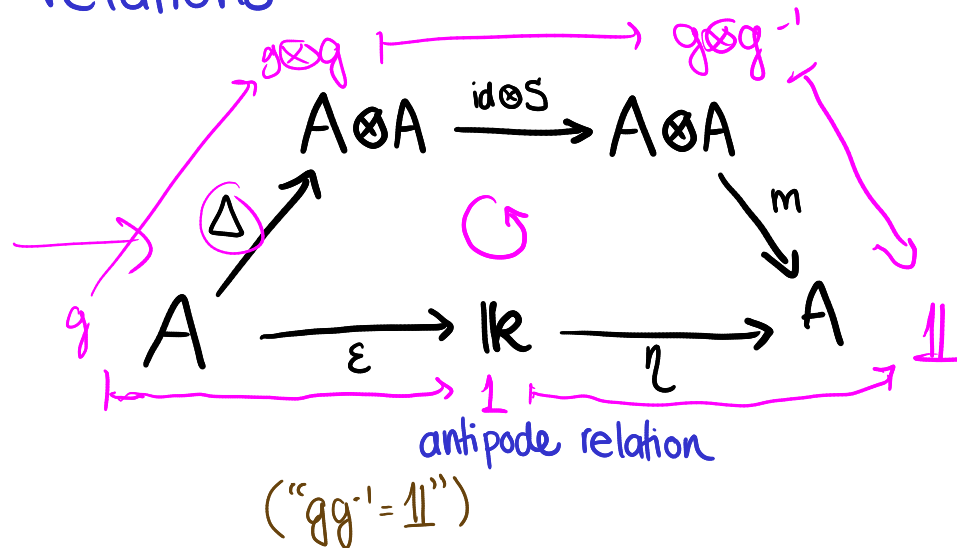
- algebra structure m, η

- coalgebra structure Δ, ε

- antipode ("inverse") $S: A \rightarrow A$

$$\Delta: A \rightarrow A \otimes A$$

- relations



$$\tau(xy) = yx$$

$$\Delta(xy) = \Delta(x)\Delta(y)$$

Δ is an algebra morphism/
 m is a coalgebra morphism

Δ is an algebra morphism/
 m is a coalgebra morphism

Hopf Algebras

Examples

Group algebras

G a group, $\mathbb{K}$ a field

$$A = \mathbb{K}[G]$$

$$m(g \otimes h) = gh$$

$$\eta(\lambda) = \lambda \cdot e \quad (1 = e)$$

$$\Delta(g) = g \otimes g$$

$$\varepsilon(g) = 1 \quad \text{for } g \in G$$

$$S(g) = g^{-1} \quad \text{---}$$

Lie Algebras

$\mathfrak{g}$ Lie alg. = $\text{span}\{X, Y, \dots\}$

$$A = \widehat{\mathfrak{u}(\mathfrak{g})} = \frac{\text{words in } \mathfrak{g}}{\mathbb{K}\langle X, Y, \dots \rangle} \quad [X, Y] = XY - YX$$

$$m(X \otimes Y) = \underline{XY}$$

$$\Delta(X) = \underline{X \otimes 1 + 1 \otimes X}$$

$$\varepsilon(X) = 0 \quad \text{for } X \in \mathfrak{g}$$

$$S(X) = -X \quad \text{---}$$

$$G \curvearrowright V, W$$

$$G \curvearrowright V \otimes W$$

$$g \cdot (v \otimes w) = g \cdot v \otimes g \cdot w$$

$$(g \otimes g) \cdot (v \otimes w)$$

$$(\Delta g) \cdot (v \otimes w)$$

$$G \curvearrowright \mathbb{K}$$

$$g \cdot r = r$$

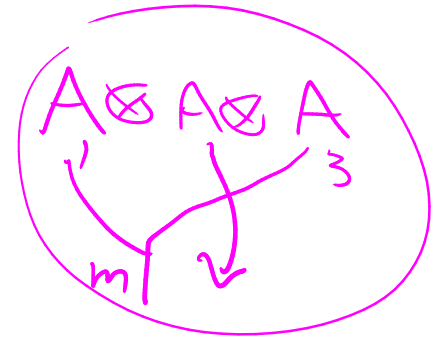
$$X \cdot (v \otimes w) = (X \cdot v) \otimes w + v \otimes X \cdot w$$

Meta-Hopf Algebras

Label tensor factors with elements of a finite set:

Instead of $\underbrace{A \otimes A \otimes A}_{\{1,2,3\}} = \underbrace{A^{\otimes 3}}$

$$\leadsto \underbrace{A_i \otimes A_j \otimes A_k}_{\{i,j,k\}} = \underbrace{A^{\otimes \{i,j,k\}}}$$



Instead of $m: \underline{A \otimes A} \rightarrow \underline{A}$

$$\leadsto \underline{m_{ij}^k: A^{\otimes \{i,j\}} \rightarrow A^{\otimes \{k\}}}$$

$$\underline{A^{\otimes \emptyset} := \mathbb{k}}$$

Instead of a v.s. $\underline{A}$ and tensors $\underline{A^{\otimes 2}}, \underline{A^{\otimes 3}}, \dots$

$\leadsto$ For S a finite set, assign A_S a set.

$$(\underbrace{A, A^{\otimes n}}_{\text{v.s.}}, \underbrace{m, \Delta, \eta, \varepsilon, S}_{\text{tensors}})$$

$$(\underbrace{\{A_S\}_{S \text{ fin set}}}_{\text{v.s.}}, m_{ij}^k, \Delta_{jk}^i, \eta_k, \varepsilon^i, S_i^i)$$

$$m_{ij}^k: A^{\otimes \{i,j\} \cup S} \rightarrow A^{\otimes \{k\} \cup S}$$

$$\eta_k: A^{\otimes S} \rightarrow A^{\otimes S \cup \{k\}}$$

$$\eta_k: A_S \rightarrow A_{S \cup \{k\}}, \eta_k: A_\emptyset \rightarrow A_{\{k\}}$$

Meta-Hopf Algebras

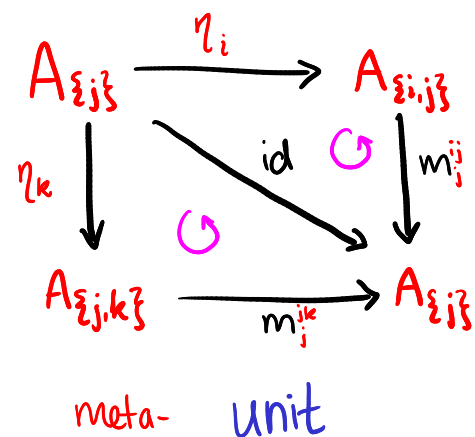
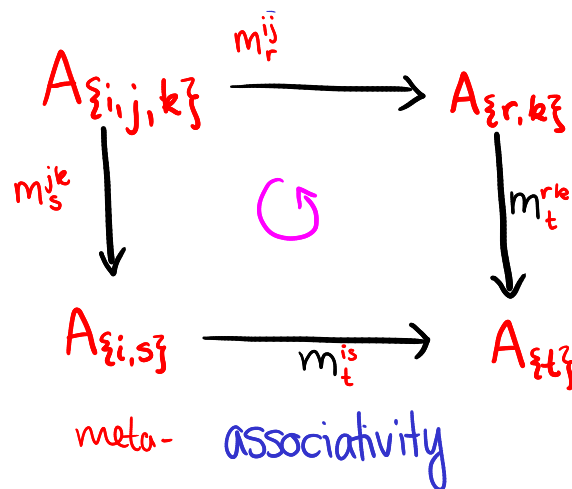
① meta-algebra structure:

- Set A and ~~associated sets~~ ~~tensor products~~ $A_{\{i,j\}}$, $A_{\{i,j,k\}}$, A_S for $|S| < \infty$
 ~~$A \otimes A$, $A \otimes A \otimes A, \dots$~~

• meta-multiplication $A_{\{i,j\}} \xrightarrow{m_k^{ij}} A_{\{k\}}$

• meta-unit a map $A_\emptyset \xrightarrow{\eta_i} A_{\{i\}}$ (define $1 := \eta(1) \in A$)

• relations:



Meta-Hopf Algebras

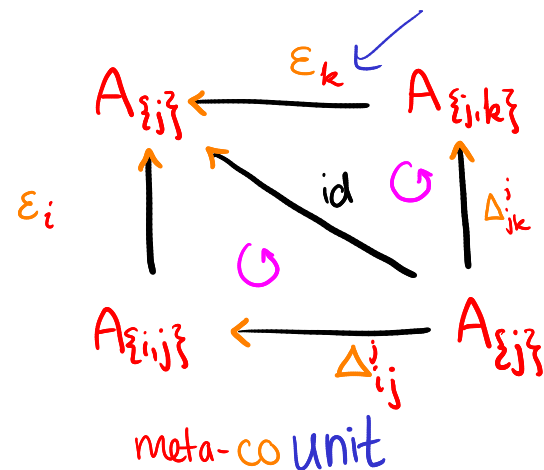
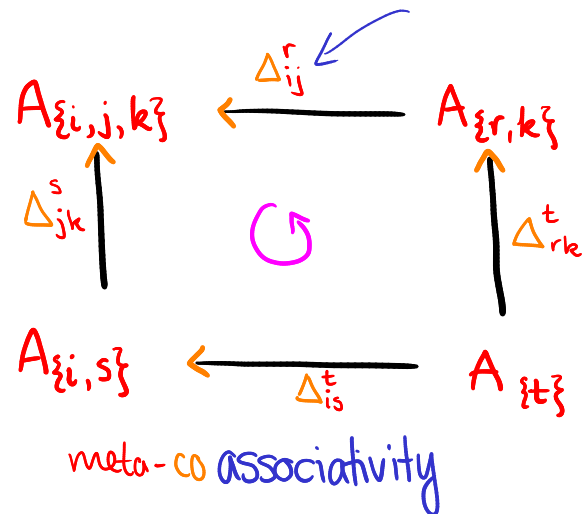
② meta-co algebra structure:

- Set A and ~~tensor products~~ $A_{\{i,j\}}$, $A_{\{i,j,k\}}$, A_S for $|S| < \infty$

- meta-co multiplication $A_{\{i,j,k\}} \xleftarrow{\Delta_{j,k}^i} A_{\{i\}}$

- meta-co unit a map $A_{\emptyset} \xleftarrow{\varepsilon^i} A_{\{i\}}$

• relations:



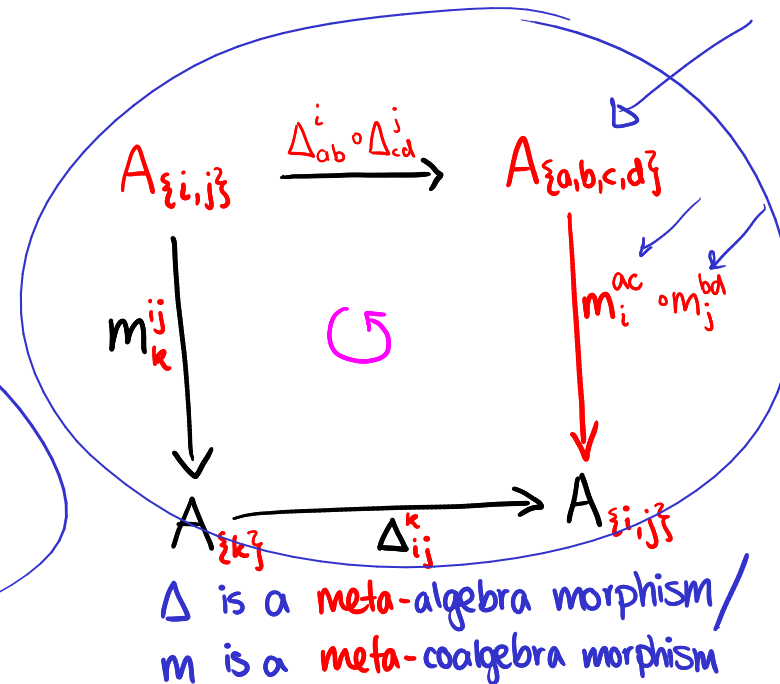
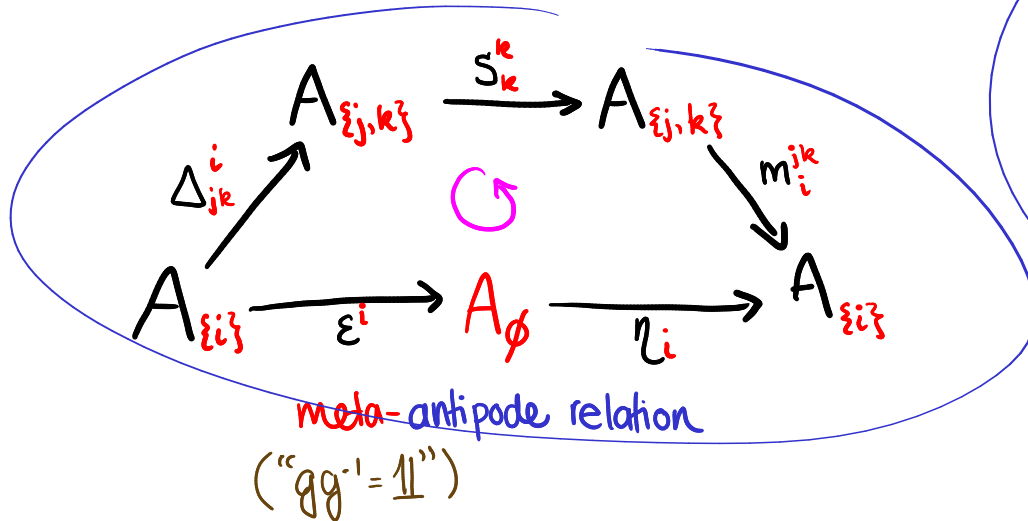
Meta-Hopf Algebras

$$|S| = |\tau|$$

$$A_S \cong A_\tau$$

③ **meta-bi** algebra structure:

- vector space $A_{\{i,j\}}$ and tensor products $A \otimes A, A \otimes A \otimes A, \dots$
- **meta**-algebra structure m_{ij}^k, η_i
- **meta**-coalgebra structure $\Delta_{jk}^i, \varepsilon^i$
- **meta**-antipode ("inverse") $S_i^j: A_{\{i,j\}} \rightarrow A_{\{j,i\}}$
- relations



$$\tau(xy) = y \otimes x$$

unnecessary!

Meta-Hopf Algebras

Examples

Group algebras

G a group, $\mathbb{k}$ a field

$$A_S = \mathbb{k}[G]^{\otimes S}$$

$$m_{ij}^k(g_i, h_j) = g_k h_k$$

$$\eta_i(\lambda) = \lambda \cdot e_i$$

$$\Delta_{jk}^i(g_i) = g_j g_k$$

$$\varepsilon^i(g_i) = 1 \quad \text{for } g \in G$$

$$S_i^i(g_i) = g_i^{-1} \quad \text{---''---}$$

Lie Algebras

$\mathfrak{g}$ Lie alg.

$$A_S = \widehat{\mathcal{U}}_{\hbar}(\mathfrak{g})^{\otimes S}$$

$$m_{ij}^k(X_i, Y_j) = X_k Y_k$$

$$\Delta_{jk}^i(X_i) = X_j + X_k$$

$$\varepsilon^i(X_i) = 0 \quad \text{for } X \in \mathfrak{g}$$

$$S_i^i(X_i) = -X_i \quad \text{---''---}$$

(virtual) tangles (vT)

$A_S = \{ \text{open tangles with components} \}$
indexed by S

$$m_{ij}^k \left(\begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array} \right) = \begin{array}{c} \nearrow_k \\ \nwarrow_k \end{array}$$

$$\eta_k \left(\begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array} \right) = \begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_k \end{array}$$

$$\Delta_{ab}^i \left(\begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array} \right) = \begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_a \nearrow_b \end{array}$$

$$\varepsilon^i \left(\begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array} \right) = \begin{array}{c} \nearrow_j \\ \nwarrow_j \end{array}$$

$$S_i^i \left(\begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array} \right) \approx \begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array}$$

$$\begin{array}{c} \nearrow_i \searrow_j \\ \nwarrow_i \nearrow_j \end{array} \in A_{\{i,j\}}$$

Meta-Hopf Algebras

Examples

The important algebra example:

$$\mathfrak{g} = \langle y, b, a, x \rangle \Big/ \begin{array}{l} [a, x] = x \\ [a, y] = -y \\ [x, y] = b \\ b \text{ is central} \end{array}$$

Let $U = \underline{U}(\mathfrak{g})[[\hbar]] = \widehat{U}(\mathfrak{g}) =$ power series in y, b, a, x

$$U_S = U^{\otimes S} = \langle y_i, b_i, a_i, x_i \rangle_{i \in S} \Big/ (\text{different indices commute})$$

$$y_i \otimes x_j =: \underline{\underline{y_i x_j}}$$

e.g.

$$i \neq j \Rightarrow x_i y_j = y_j x_i$$

Thm

There is a morphism of meta-Hopf algebras:

$$Z: \text{vT} \longrightarrow \text{u}$$

$$\begin{array}{c} \text{Diagram 1: Crossing with } i \text{ on left, } j \text{ on right} \\ \hline \longrightarrow e^{\underline{a_j b_i + y_i x_j}} =: R_{ij} \end{array}$$

$$\begin{array}{c} \text{Diagram 2: Crossing with } j \text{ on left, } i \text{ on right} \\ \hline \longrightarrow e^{\underline{-a_j b_i - y_i x_j} e^{b_i}} =: \bar{R}_{ij} \end{array}$$

which is also invariant



$$R_{ij}^{-1} = \bar{R}_{ij}$$

$$\text{Diagram 1} = \text{Diagram 2}$$

Yang-Baxter equation for R_{ij}

This is topological, but is it efficient?

Computational optimization

$$Z\left(\begin{array}{c} \text{diagram of a knot with a blue arrow labeled } i \end{array}\right) = Z\left(\begin{array}{c} \text{diagram of a knot with blue arrows labeled } a, b, c, d, e, f \end{array}\right) = \underbrace{\bar{R}_{ad} \bar{R}_{eb} \bar{R}_{cf}}_{\in \mathcal{U}^{\otimes \{a,b,c,d,e,f\}}} \parallel m_i^{ab} \parallel m_i^{ic} \parallel m_i^{id} \parallel m_i^{ie} \parallel m_i^{if}$$

The bracket relations $[a, x] = x, \dots$ allow us to choose an ordering of monomial factors.
 $\alpha x = x \alpha + x$

$$\leadsto \mathcal{U}(\mathfrak{g}) \cong \underline{k[y, b, a, x]} \text{ as } \underline{\text{vector spaces}}$$

Q: How do we compute maps between power series rings quickly?

The $\text{hom} - \otimes$ adjunction

Fact

Given vector spaces U, V, W
 $\text{hom}(U \otimes V, W) \cong \text{hom}(V, \text{hom}(U, W))$

We can identify linear maps $V \longrightarrow W$
 with elements of $\underline{V^* \otimes W}$

The map $\underline{m_k^{ij} : U^{\otimes\{i,j\}} \rightarrow U^{\otimes\{k\}}}$ can be re-interpreted as $\underline{m_k^{ij} \in (U^*)^{\otimes\{i,j\}} \otimes U^{\otimes\{k\}} =: U^{\otimes\{i^*, j^*, k\}}}$
 (exponential generating functions)

Fact (composing maps)

Given $\varphi : \mathbb{K}[X] \rightarrow \mathbb{K}[Y]$

(i.e. $\varphi \in \mathbb{K}[X^*, Y]$) and $f \in \mathbb{K}[X]$

$$\text{ev}_f(\varphi) = \varphi(f) = \left(\varphi \Big|_{X^* = \frac{\partial}{\partial X}} \right) (f) \Big|_{\underline{X=0}}$$

$$\begin{aligned} \langle (X^*)^n, X^m \rangle &= \delta_{n,m} n! \\ &= \frac{\partial^n}{\partial X^n} X^m \Big|_{X=0} \end{aligned}$$

Composing generating functions

$$\text{In } \mathcal{U}(\sigma_j), m_{jk}^{ij} = e^{(y_i^* + \frac{e^{-a_i^*}}{0} y_j^*) y_k + (b_i^* + b_j^*) b_k + (a_i^* + a_j^* + y_j^* x_i^*) a_k + (e^{-a_j^*} x_i^* + x_j^*) x_k}$$

Putting weights on the variables such that:

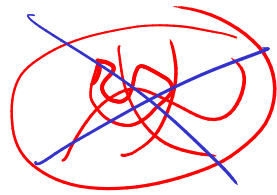
- $\text{wt}(c_i) + \text{wt}(c_i^*) = 2$ for all $c \in \{y, b, a, x\}$
- $\text{wt}(x_i) = \text{wt}(y_i) = 1, \text{wt}(b_i) = 0, \text{wt}(a_i) = 2$

$\Rightarrow m_{jk}^{ij}$ is of the form e^Q for a quadratic Q

[more computation] $\Rightarrow \Delta_{jk}^i, \eta_i, \varepsilon^i, S_i^i, R_{ij}$ are all Gaußians!

Quadratics grow quadratically

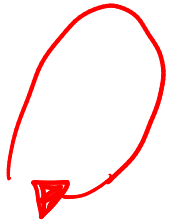
Traces



For matrices $(AB)_{ik} = \sum_j a_{ij} b_{jk}$ and

$$\text{tr}(A) = \sum_i a_{ii}$$

~> multiplication glues two matrices together
traces glue a matrix to itself



For knots $m_{ij}^k(\text{diagram}) = \text{diagram}$ and $\text{tr}_i(\text{diagram}) = \text{diagram}$

For a general algebra A , a trace on A is a coequalizer $A \otimes A \xrightarrow[m^{\text{op}}]{m} A \xrightarrow{\text{tr}} A_A$
invariants of A

$$q \oint \vec{A} = R \cdot m_k^{ij}$$